# Anderson Acceleration: Software, Storage, and a Multi-Physics Example

C. T. Kelley NC State University tim\_kelley@ncsu.edu Supported by NSF, DOE, ARO

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- 2 Storage Issues in Anderson Acceleration
- 3 Conductive-Radiative Heat Transport

#### 4 Summary

-New Book

#### New Book: Great holiday gift

Fundamentals of Algorithms

Solving Nonlinear Equations with Iterative Methods Solvers and Examples in Julia



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#### Sequel to

C. T. KELLEY, Solving Nonlinear Equations with Newton's Method, number 1 in Fundamentals of Algorithms, SIAM, Philadelphia, 2003.

#### Differences

- Completely new code in Julia
- Deletion: Broyden's method
- Additions:  $\Psi TC$  + Anderson Acceleration
- Software + Jupyter notebook open source on Github



- Better mixed precision, especially half, support
   C. T. KELLEY, <u>Newton's method in mixed precision</u>, SIAM
   Review, 64 (2022), pp. 191–211.
- Jupyter notebooks
- Package infrastructure for software
- No licensing pain Good for retired people

## Three part project

#### Print book

- IJulia (aka Jupyter) notebook interactive version of print book https://github.com/ctkelley/NotebookSIAMFANL
- Julia package with solvers+test problems+examples https://github.com/ctkelley/SIAMFANLEquations.jl

Print book is for sale. Notebook and Package are free.

-New Book

### How to do projects like this

- Motivated by R. LeVeque's project:
  - Print book
  - Notebooks
  - $\blacksquare$  notebook  $\rightarrow$  print book with Python
- Mappings are different
  - $\blacksquare notebook \rightarrow print book$
  - print book  $\rightarrow$  notebook
- Many things to figure out on your own.
- Randy and Tim were both retired while doing this.

-New Book

## Coverage of Anderson Acceleration

- Nothing fancy (fixed  $\beta$ , no EDIIS, no depth management, ...)
- Theory (Basic stuff, no proofs)
- Discussion of Implementation
- CODE
- Examples

The rest of this talk is about the implementation and one example.

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#### What does AA store?

The simple version of AA fori x = G(x) is  $anderson(x_0, G, m)$ 

$$\begin{split} & \mathsf{x}_1 = \mathsf{G}(\mathsf{x}_0); \, \mathsf{F}_0 = \mathsf{G}(\mathsf{x}_0) - \mathsf{x}_0 \\ & \mathsf{for} \ k = 1, \dots \ \mathsf{do} \\ & m_k \leq \min(m, k) \\ & \mathsf{F}_k = \mathsf{G}(\mathsf{x}_k) - \mathsf{x}_k \\ & \mathsf{Minimize} \parallel \sum_{j=0}^{m_k} \alpha_j^k \mathsf{F}_{k-m_k+j} \parallel \text{ subject to } \sum_{j=0}^{m_k} \alpha_j^k = 1. \\ & \mathsf{x}_{k+1} = \sum_{j=0}^{m_k} \alpha_j^k \mathsf{G}(\mathsf{x}_{k-m_k+j}) \\ & \mathsf{end for} \end{split}$$

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#### Remember the words

- *m*, depth. We refer to Anderson(*m*).
   Anderson(0) is Picard.
- F(x) = G(x) x, residual
- $\{\alpha_j^k\}$ , coefficients Minimize  $\|\sum_{j=0}^{m_k} \alpha_j^k F_{k-m_k+j}\|$  subject to  $\sum_{j=0}^{m_k} \alpha_j^k = 1$ . is the optimization problem.

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 is  $\ell^2$  in this talk.

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# Solving the Optimization Problem

Solve the linear least squares problem:

$$\min \left\|\mathsf{F}_{m_k} - \sum_{j=0}^{m_k-1} \alpha_j^k (\mathsf{F}_{k-m_k+j} - \mathsf{F}_k)\right\|_2^2,$$

for  $\{\alpha_j^k\}_{j=0}^{m_k-1}$  and then

$$\alpha_{m_k}^k = 1 - \sum_{j=0}^{m_k-1} \alpha_j^k.$$

More or less what's in the codes, BUT ...

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- you have to store
  - Coefficient matrix for the optimization problem F
  - Iteration history G
- So a minimum of 2m + O(1) vectors.
- Even if you manage  $m_k \leq m$ , you must store 2m vectors.
- Many physics codes use the normal equations and get 2m.
   Example RMG
- But the coefficient matrix is very ill-conditioned ....

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# Walker-Ni Formulation: I

Maintain a QR factorization of the coefficient matrix. Reformulate the optimization problem:

$$\min_{\theta \in R^{m_k}} \|\mathsf{F}(\mathsf{x}_k) - \sum_{j=0}^{m_k-1} \theta_j(\mathsf{F}(\mathsf{x}_{k-m_k+j+1}) - \mathsf{F}(\mathsf{x}_{k-m_k+j}))\|$$

for  $\theta^k \in R^{m_k}$  then

$$x_{k+1} = G(x_k) - \sum_{j=0}^{m_k-1} \theta_j^k (G(x_{k-m_k+j+1}) - G(x_{k-m_k+j})).$$

In terms of the original formulation

$$\alpha_0 = \theta_0, \alpha_j = \theta_j - \theta_{j-1} \text{ for } 1 \le j \le m_k - 1 \text{ and } \alpha_{m_k} = 1 - \theta_{m_k-1}.$$

# Walker-Ni Formulation: II

Let  $D_F^k$  and  $D_G^k$  have columns

$$(\mathsf{D}_F^k)_j = \mathsf{F}(\mathsf{x}_{k-m_k+j+1}) - \mathsf{F}(\mathsf{x}_{k-m_k+j})$$

and

$$(\mathsf{D}_G^k)_j = \mathsf{G}(\mathsf{x}_{k-m_k+j+1}) - \mathsf{G}(\mathsf{x}_{k-m_k+j}).$$

Then the optimization problem is

$$\min \|\mathsf{F}(\mathsf{x}_k) - \mathsf{D}_F^k \theta^k\|$$

and

$$\mathsf{x}_{k+1} = \mathsf{G}(\mathsf{x}_k) - \mathsf{D}_{\mathsf{G}}^k \theta.$$

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# Walker-Ni Formulation: III

Walker-Ni update the QR factorization of  $D_F^k$ .

- Update D<sub>G</sub> by adding a new column and deleteing the leading column (if k > m<sub>k</sub> − 1) if necessary.
- Update D<sub>F</sub> by adding a new column and deleting the old column if necessary.

Updating the QR factorization of  $D_F$  is tricky ...

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# Walker-Ni Formulation: IV

- If k > m<sub>k</sub> − 1 you have to update QR to be the factorization of D<sub>F</sub> with the first column deleted.
- After that update QR with the new column via Gram-Schmidt I like classical GS twice.

The story of the downdate is ...

# Walker-Ni Formulation: IV

Suppose A = QR is the QR factorization of an  $N \times m$ 

$$\mathsf{A} = (\mathsf{a}_1, \mathsf{a}_2, \dots, \mathsf{a}_m) = \mathsf{Q}\mathsf{R} = \mathsf{Q}(\mathsf{r}_1, \mathsf{r}_2, \dots, \mathsf{r}_m).$$

# I want the QR factorization of = (a<sub>2</sub>,..., a<sub>m</sub>) Let R = (r<sub>2</sub>,..., r<sub>m</sub>), then = QR.

- Factor  $\tilde{R} = Q^1 \hat{R}$ . Let  $\hat{Q} = QQ^1$ .
- Then  $\hat{A}=\hat{Q}\hat{R}$  is the QR factorization of  $\hat{A}$

# Storage Problem!

- You must allocate storage for both  $\hat{Q}$  and  $QQ^1$ ,
- then you can overwrite Q with Q.
- So with AA you are now at 3*m* vectors.
- But there's a hack ...
   Compute the product QQ<sup>1</sup> in blocks of rows.
   Overwrite the rows of Q as you progress.
   Slower, but the storage is back under control.
- There's always the normal equations.

- Conductive-Radiative Heat Transport

# Conductive-Radiative Heat Transport

#### (Siewert-Thomas, 91)

- System of two equations
  - Linear Boltzmann transport equation
  - Heat Equation
- Household insulation is the 2D problem
- Coupling via "radiation proportional to 4th power of temperature"
- I'm a mathematician, so it's 1-D in space.
- There's Julia code for all of this in the repo.

#### Geometry and unknowns

- Unknowns:
  - Dimensionless radiation intensity  $\psi(x,\mu)$  (angular flux)
  - Dimensionless temperature  $\Theta(x)$
- Radiation depends on direction.

Stand in the sun if you don't believe that.

- $\mu$  is cosine of direction angle.  $\mu > 0$  means from the left.
- $\mu < 0$  means from the right.

## Transport Equation

$$\mu \frac{\partial \psi}{\partial x}(x,\mu) + \psi(x,\mu) = \frac{\omega}{2} \int_{-1}^{1} \psi(x,\mu') \, d\mu' + (1-\omega) \Theta^4(x)$$

for  $x \in (0, \tau)$ .  $0 < \omega \leq 1$  and the boundary conditions are

$$\psi(0,\mu)=\Theta_l^4,\ \mu>0 ext{ and } \psi( au,\mu)=\Theta_r^4,\ \mu<0.$$

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- Conductive-Radiative Heat Transport

#### Some facts about transport with $\Theta$ given

Trust me on this. Details in the book.

Given  $\Theta$  the transport equation is a linear equation for f

Can formulate as a linear equation for the scalar flux

$$f(x) = \frac{1}{2} \int_{-1}^{1} \psi(x, \mu') \, d\mu'$$

The operator is a compact perturbation of the identity, so ...

GMRES works very well as a solver.

## Heat equation

$$rac{\partial^2 \Theta}{\partial x^2} = Q(x), x \in [0, \tau], \ \Theta(0) = \Theta_I, \Theta(\tau) = \Theta_r$$

where

$$Q(x) = \alpha(x)(\Theta^{4}(x) - f(x)), 0 < x < \tau, f(x) = \frac{1}{2} \int_{-1}^{1} \psi(x, \mu') \, d\mu'$$

and

$$\alpha(\mathbf{x}) = (1-\omega)/N_c.$$

 $N_c$  is the conduction to radiation parameter.

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- Conductive-Radiative Heat Transport

# Compact fixed point formulation: $\Theta = \mathcal{G}(\Theta)$

- Given Θ solve the transport equation with an iterative method to obtain f.
- 2 Use the solution f of the transport equation from step 1 to compute Q = α(Θ<sup>4</sup> f).
- **3** Compute  $\mathcal{G}(\Theta) = T$  as the solution of the heat equation.

$$rac{\partial^2 T}{\partial x^2} = Q(x), x \in [0, \tau], \ T(0) = \Theta_I, T(\tau) = \Theta_r$$

We choose to **expose**  $\Theta$ . Exposing *f* is ok.

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- N = 1001 point uniform grid in space
- Discrete ordinates Sn method for transport
  - Double (20 pt) Gauss quadrature rule in angle
- Central difference for heat equation.



Problem parameters:  $\tau$ ,  $\omega$ ,  $N_c$ ,  $\theta_r$ ,  $\theta_l$ Three problems Easy:  $N_c = .05, \omega = .9, \tau = 1, \Theta_l = 0, \Theta_r = 0$ Less Easy :  $N_c = .05, \omega = .9, \tau = 2, \Theta_l = 0, \Theta_r = 1.8$ Hard:  $N_c = .05, \omega = .9, \tau = 4, \Theta_l = 0, \Theta_r = 2.0$ Compare AA(*m*) for several *m* with Newton-GMRES

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# Easy Problem



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- Conductive-Radiative Heat Transport

#### Less Easy Problem: not contractive



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# Hard Problem: really not contractive



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- New book: Codes + Examples in Julia
- Storage: Needs thought
- Multi-Physics Example: Conductive-Radiative Heat Transport AA is not always the thing to do.